

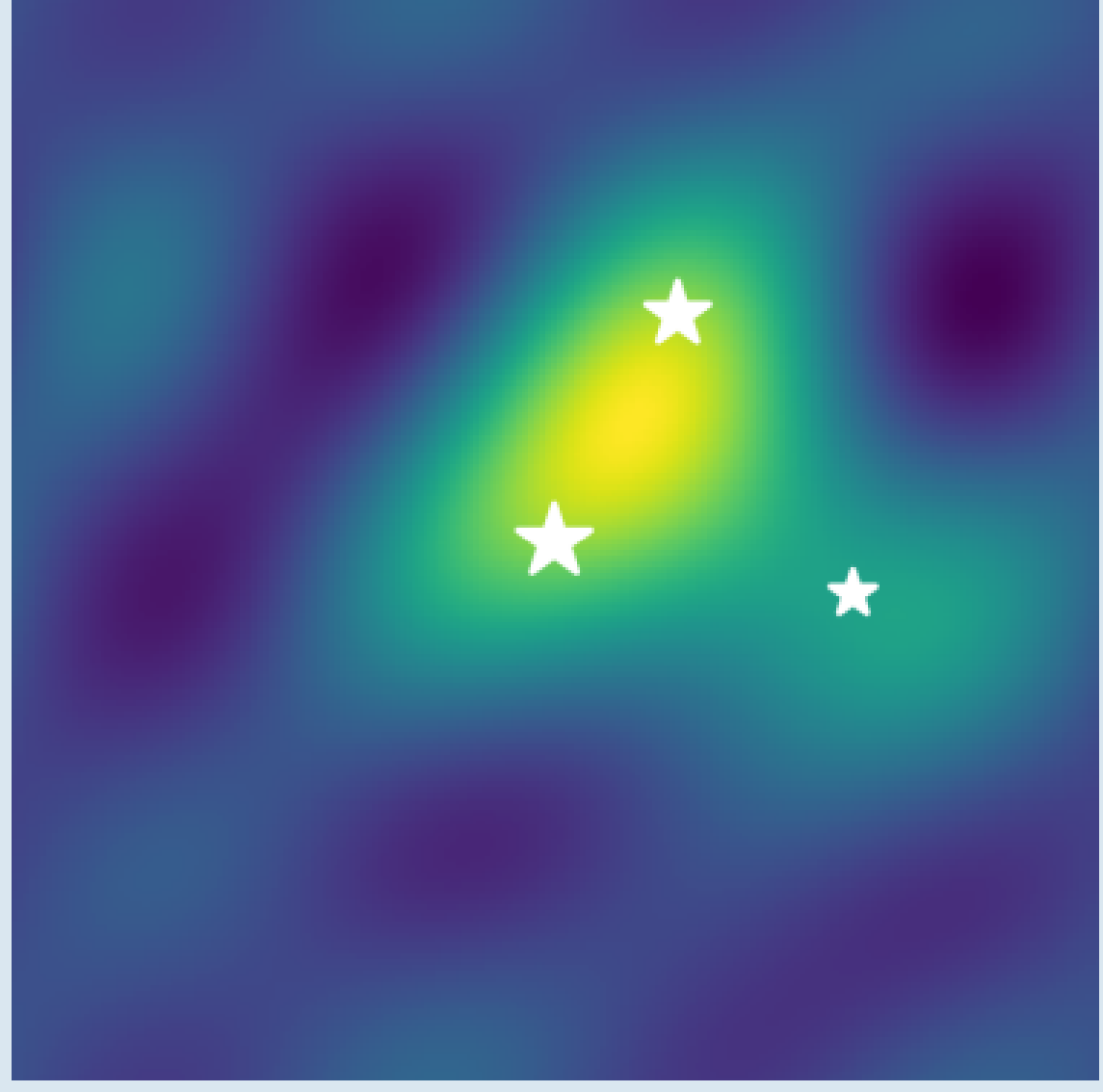
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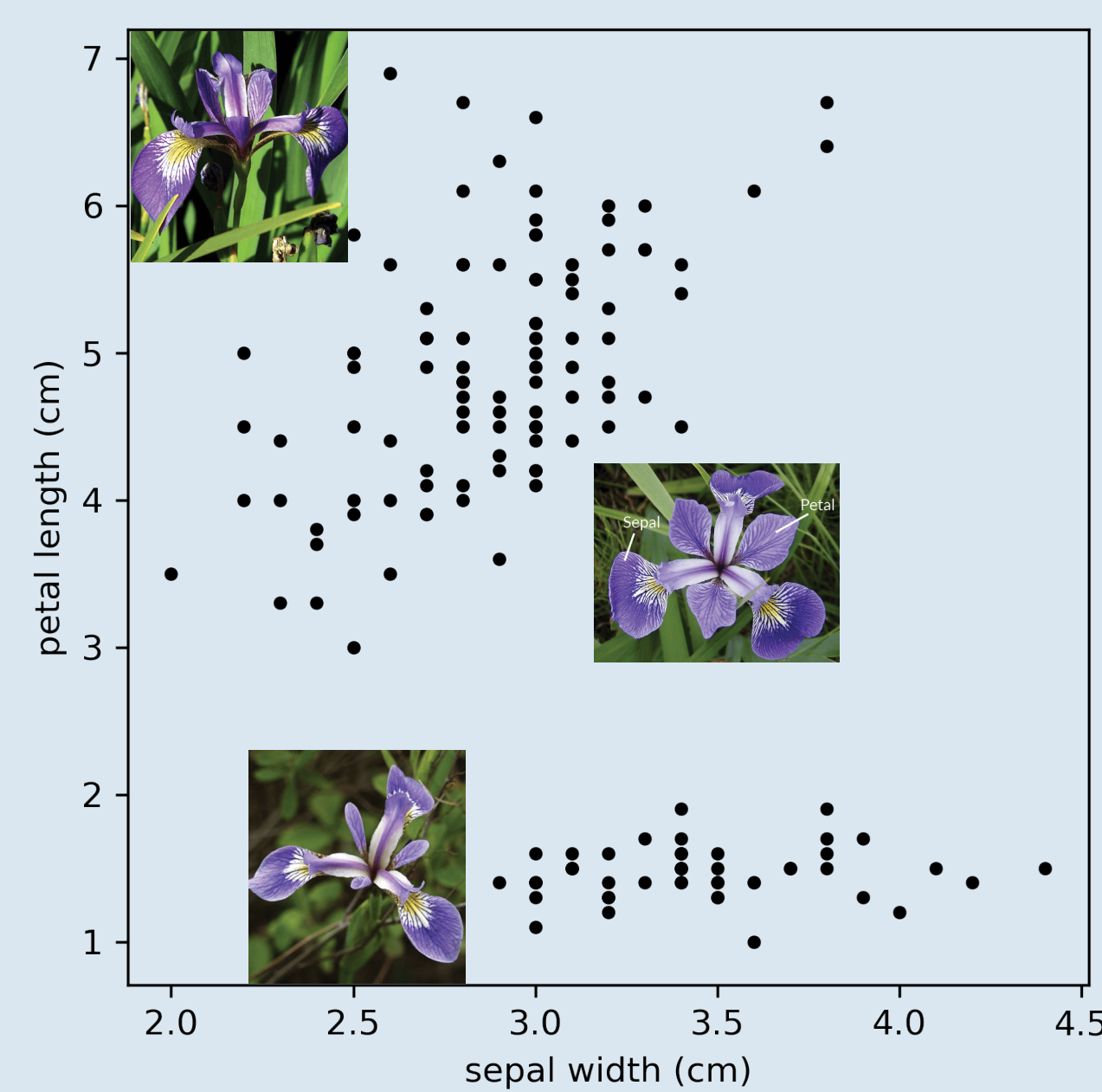
## Inverse problem

Recover a discrete object from obs.

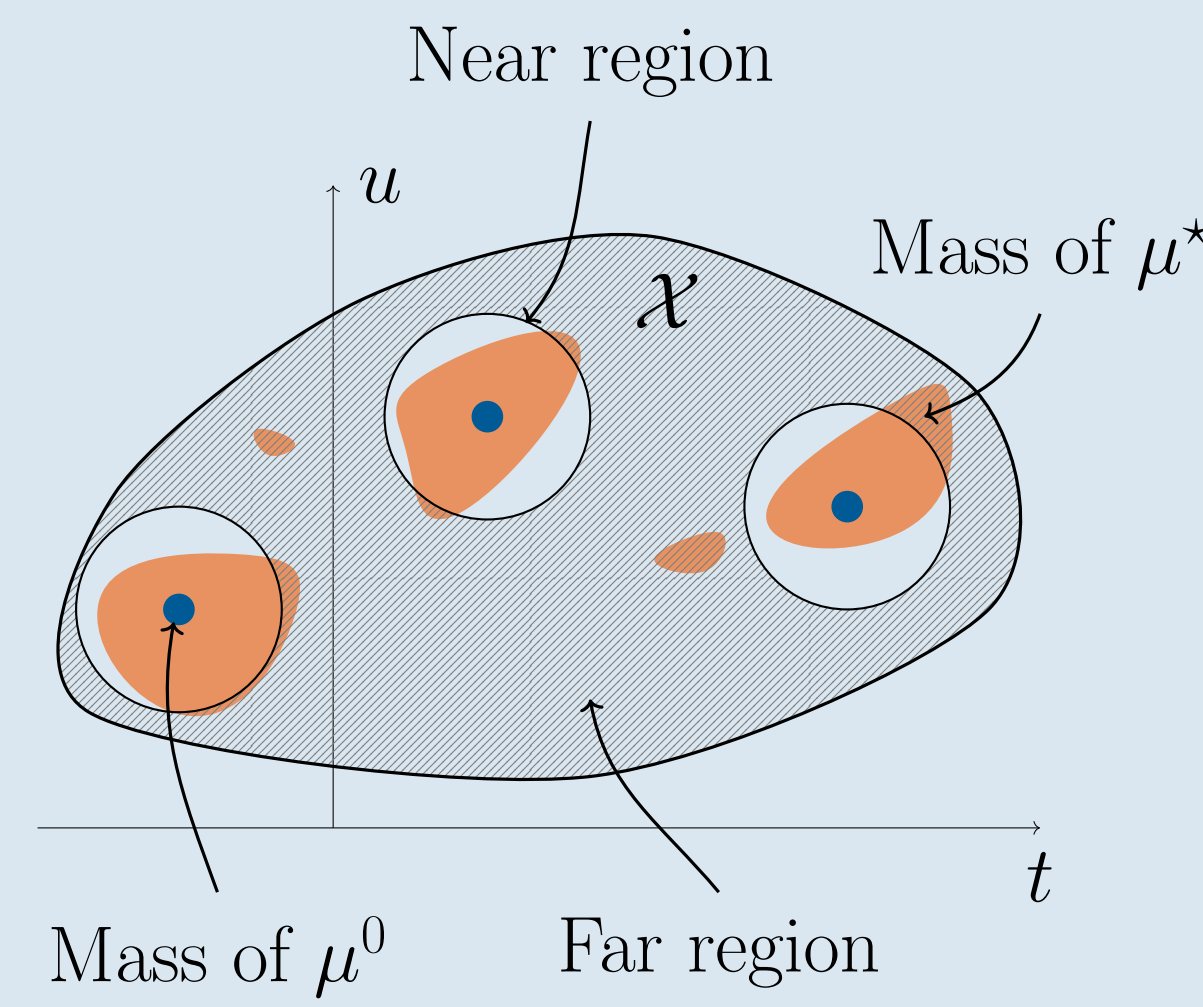


## Statistical estimation

$$X_i \in \mathbb{R}^d \stackrel{i.i.d.}{\sim} f^0$$



## Statistical guarantees



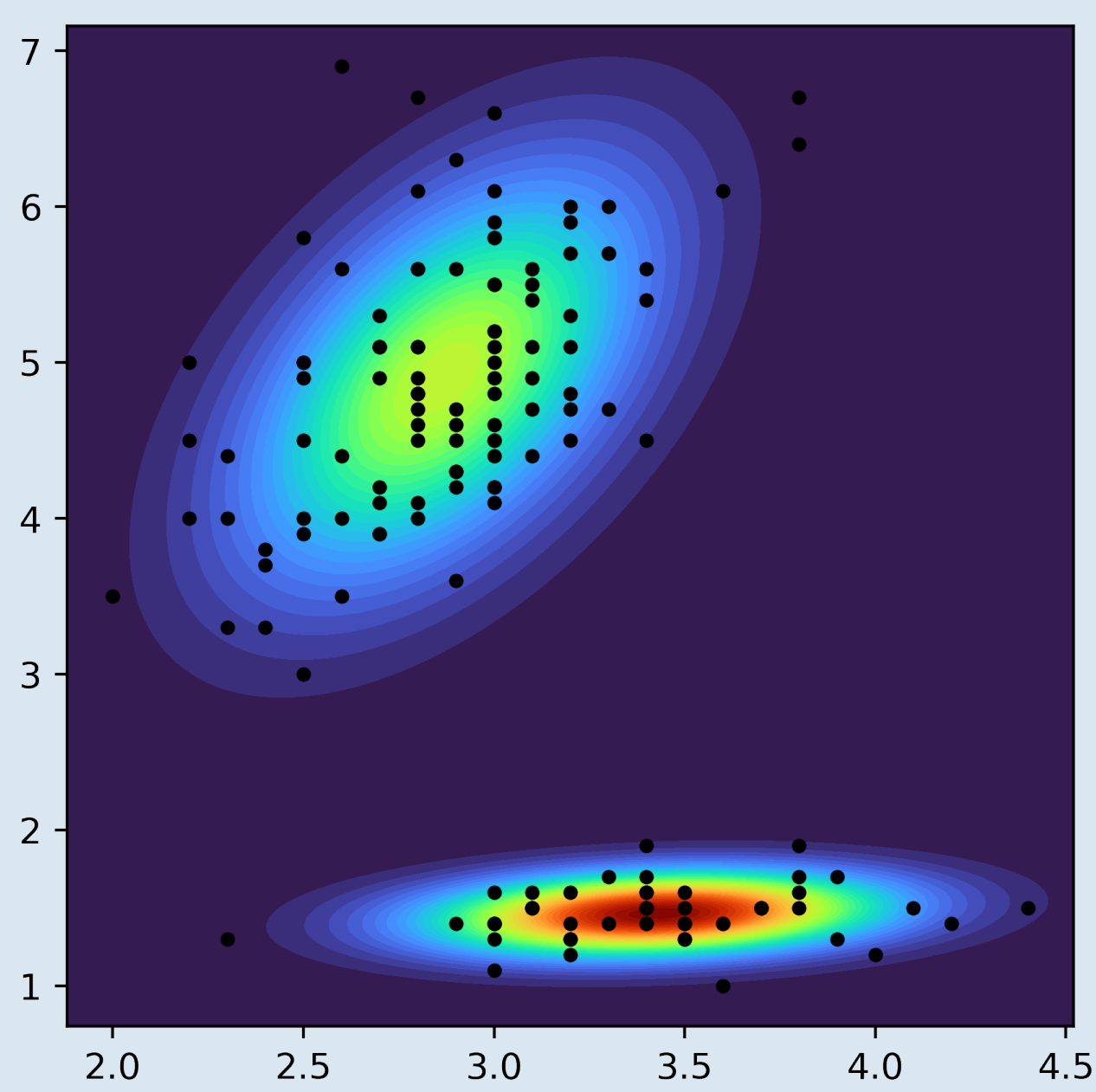
### Assumptions:

- Diagonal covariance matrices;
- Component separation;
- Suitable choices of  $\kappa$  and  $\gamma$ .

**Result:** The expected discrepancy in mass assigned to regions of the parameter space between  $\mu_\omega^0$  and a BLASSO solution  $\mu^*$  scales as  $\mathcal{O}\left(\frac{1}{\sqrt{n}}\right)$  ( $n$ : sample size).

We estimate  $\mu_\omega^0$  rather than  $\mu^0$  (technical).

## Gaussian mixture distribution



**Assumption:**  $f^0$  is the density of a Gaussian mixture distribution.

$$f^0 = \sum_{j=1}^s a_j^0 \varphi_{(t_j^0, U_j^0)}$$

where  $a_j^0 > 0$  and  $\sum_{j=1}^s a_j^0 = 1$ .

$\varphi_{(t,U)}$ : density of a  $d$ -dimensional Gaussian distribution, with mean  $t \in \mathbb{R}^d$  and square root of covariance  $U \in \mathbb{S}_{++}^d$ .

**Sample from  $f^0$ :**  $j \in \{1, \dots, s\}$  is chosen with prob.  $a_j^0$ ; then  $X_i | j \sim \varphi_{(t_j^0, U_j^0)}$ .

## Algorithm: CPGD

**Goal:** Approximate numerically the solution to the BLASSO.

**Limitation:** Must discretize  $\rightarrow J$  is no longer convex on the space of discrete measures.

**Algorithm:** Relies on *Conic retraction* and *Natural gradient descent*.

Notations: •  $J'_\mu$ : Fréchet derivative of  $J$  at point  $\mu$ .

•  $\nabla^g$ : Riemannian gradient w.r.t. Fisher-Rao geometry.

$\nabla^g J'_\mu(t, U) = \mathbf{g}_{(t,U)}^{-1} \nabla J'_\mu(t, U)$  with  $\mathbf{g}$  the metric tensor.

For diagonal covariance matrices

**Require:** Step sizes  $\alpha, \beta \geq 0$ , number of iterates  $K$ , initialization  $\mu_\omega^1 = \sum_{j=1}^p \omega_j^1 \delta_{(t_j^1, U_j^1)}$

**for**  $k = 1, \dots, K$  **do**

**for**  $j = 1, \dots, p$  **do**

$$\omega_j^{k+1} \leftarrow \omega_j^k e^{-\alpha J'_{\mu_\omega^k}(t_j^k, U_j^k)}$$

$$(t_j^{k+1}, U_j^{k+1}) \leftarrow (t_j^k, U_j^k) - \beta \nabla^g J'_{\mu_\omega^k}(t_j^k, U_j^k)$$

▷ Weight update

▷ Location-scale update

**end for**

$$\mu_\omega^{k+1} \leftarrow \sum_{j=1}^p \omega_j^{k+1} \delta_{(t_j^{k+1}, U_j^{k+1})}$$

**end for**

## Goal: Estimation of a Gaussian mixture model

**Goal:** Recover the parameters of the mixture from the data  $X_1, \dots, X_n$ .

**Parameters:** Number of components  $p$  (unknown),  $(a_j)_{j=1}^p, (t_j, U_j)_{j=1}^p$ .

	Convex	Do not require knowledge of $p$
Log-likelihood maximization (EM algo.)	✗	✗
BLASSO	✓	✓

## The Beurling-LASSO (BLASSO)

**Main idea:** Embed the Gaussian mixture parameters into a measure:

$$(a_j, t_j, U_j)_{j=1}^p \mapsto \mu = \sum_{j=1}^p a_j \delta_{(t_j, U_j)}$$

The goal is to recover the target measure  $\mu^0 = \sum_{j=1}^s a_j^0 \delta_{(t_j^0, U_j^0)}$ .

**Loss function:** Combines a *data fidelity term* and a *regularization term*.

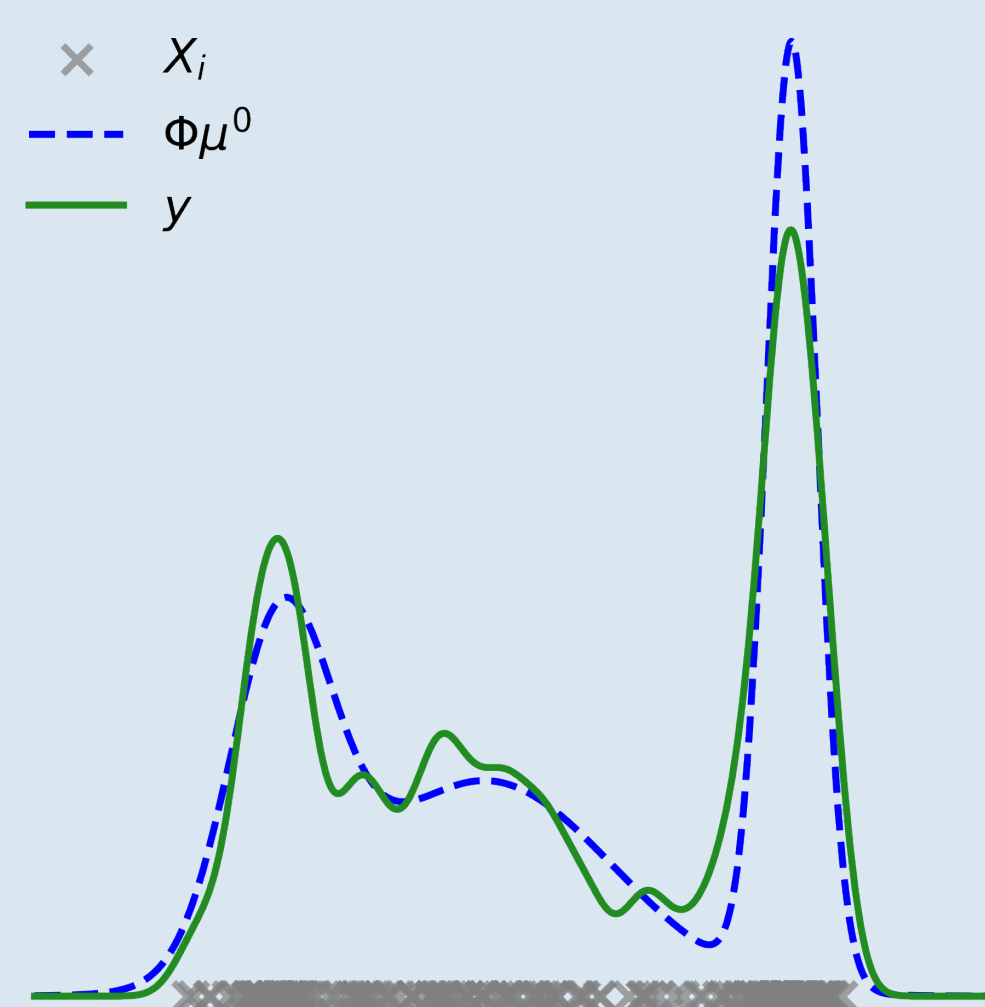
**Data fidelity term:** Ensures the estimate fits the observations.

• Rewrite  $f^0 = \Phi \mu^0$  with  $\Phi$  a linear map from measures to functions.

• Construct an approximation  $y$  of  $f^0$  from the observations  $X_1, \dots, X_n$  (convolution with Gaussian kernel).

• For any candidate measure  $\mu$ , evaluate  $\|\Psi \mu - y\|_{\mathbb{L}}^2$  ( $\mathbb{L}$ : Hilbert space).

$\Psi$ : smoothing of  $\Phi$



**Regularization term:** Promotes sparsity.

Total variation norm: for a discrete measure  $\mu = \sum_{j=1}^p a_j \delta_{(t_j, U_j)}$ ,

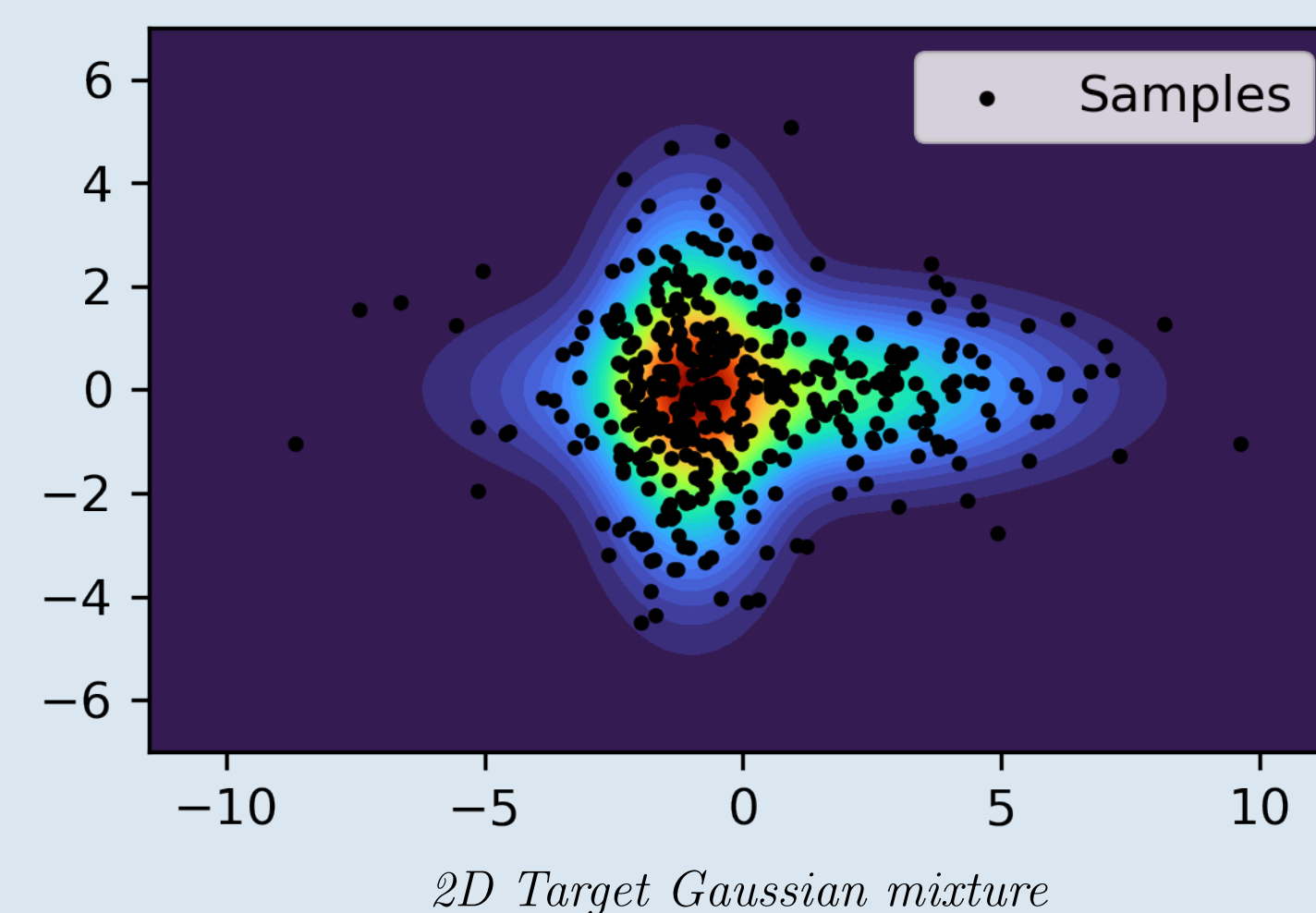
$$\|\mu\|_{\text{TV}} = \sum_{j=1}^p |a_j|.$$

**The BLASSO:** Regularization parameter  $\kappa > 0$ .

$$\arg \min_{\mu \in \mathcal{M}(\mathcal{X})^+} J(\mu) \quad \text{with} \quad J(\mu) := \frac{1}{2} \|\Psi \mu - y\|_{\mathbb{L}}^2 + \kappa \|\mu\|_{\text{TV}}$$

Convex problem!

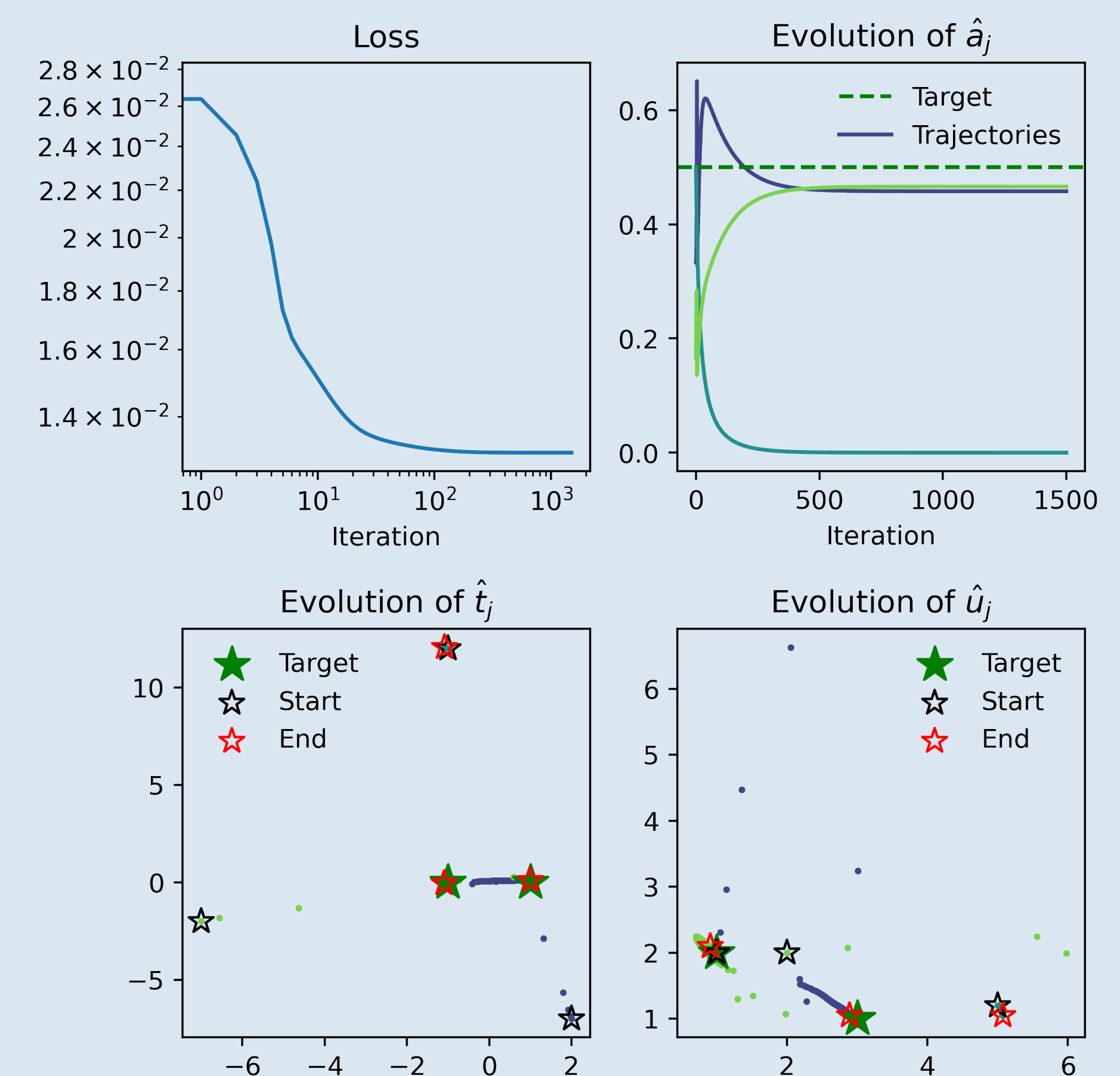
## Numerical experiment



**Setting:** Gaussian mixture in 2 dimensions, diagonal covariance matrices. 2 target components.

We have access to  $n = 400$  samples of the target mixture.

**Algo:** Initialization with 3 particles.



## References

- Poon et al. (2023), "The geometry of off-the-grid compressed sensing".
- De Castro et al. (2021), "SuperMix: Sparse Regularization for Mixtures".
- Chizat (2022), "Sparse optimization on measures with over-parameterized gradient descent".
- Nielsen (2020), "An Elementary Introduction to Information Geometry".
- **Associated paper:** Giard et al. (2025), *Gaussian Mixture Model with unknown diagonal covariances via continuous sparse regularization*. Submitted. arXiv:2509.12889